



▶ Hybrid stepper motors

6600-15

- Step angle 1.8°
- Diameter 57.2 mm
- Weight 370 g
- Holding torque ... 540/385 mNm

The hybrid stepper motor comes into its own where torque at low speed, positioning, and accuracy are determining factors.

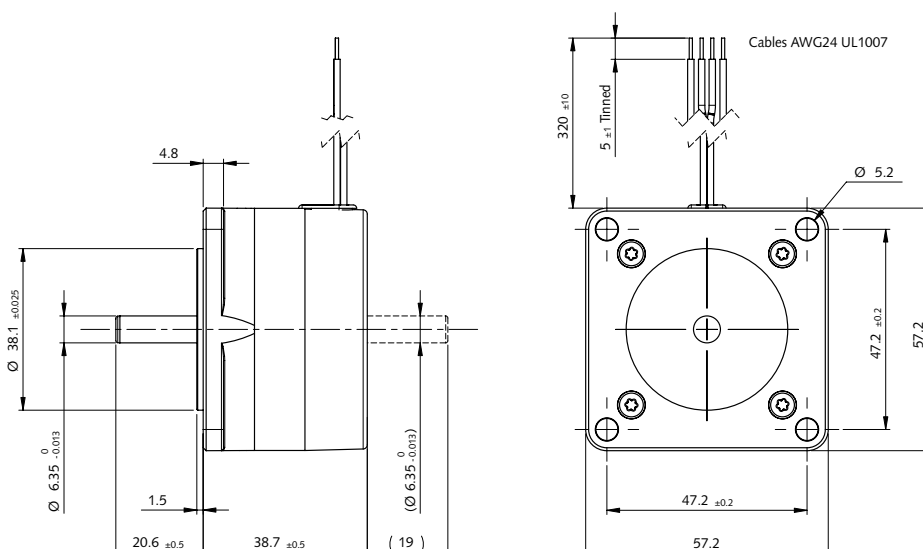
▶ Technical data

	Part N°	Phase resistance [Ω]	Phase inductance [mH]	Phase current [A]	Holding torque [mNm]	Nominal power [W]
Bipolar	6600-15-2-1.6	1.6	3.5	1.5	540	7.2
Unipolar	6600-15-4-1.6	1.6	1.7	1.5	385	7.2
	6600-15-4-13.5	13.5	13.9	0.52	385	7.2

Steps/rev.	200
Step accuracy	± 5 %
Rotor inertia	131 gcm ²
Insulation class	B 130° C
Protection	DIN 40050 IP 30
Test voltage	500 VAC
Detent torque	26 mNm

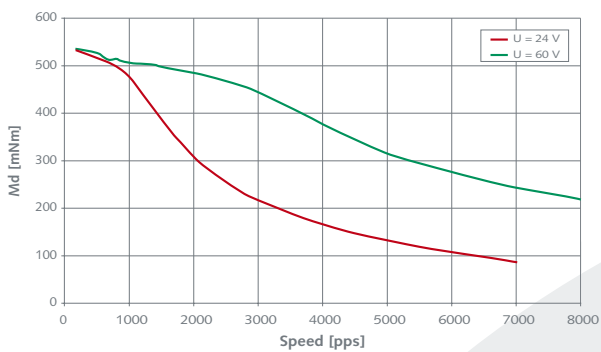
▶ Dimensions

Drawing not to scale. All dimensions in mm.



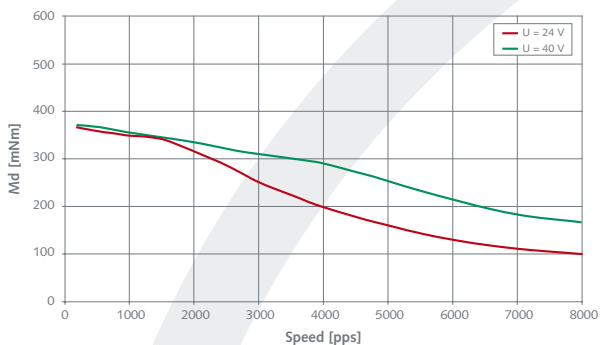
► Dynamic characteristics

• 6600-15-2-1.6

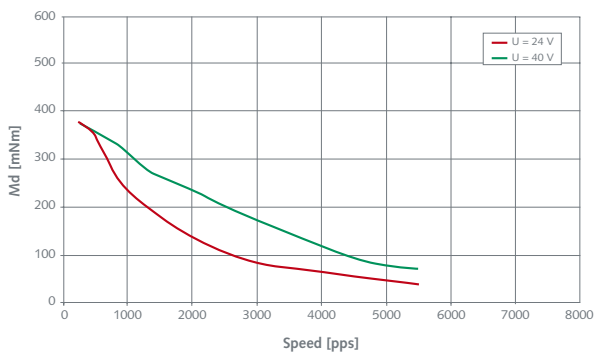


[pps] = pulses per second

• 6600-15-4-1.6

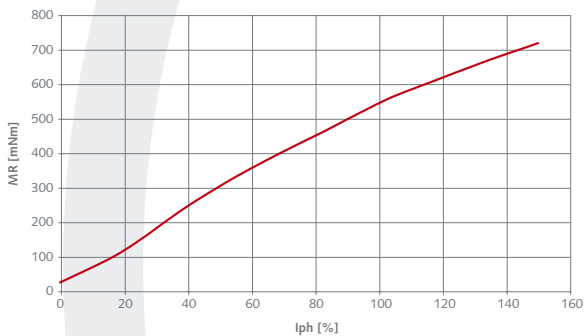


• 6600-15-4-13.5

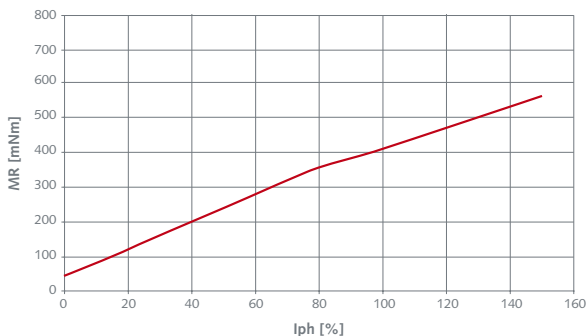


► Static characteristics

• 6600-15-2 Series

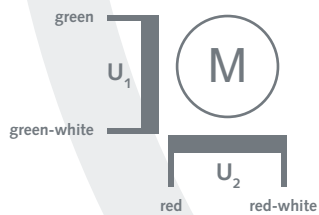


• 6600-15-4 Series

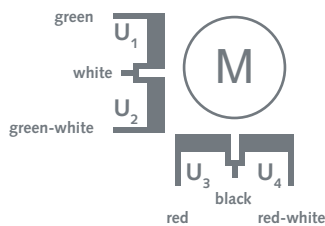


► Electrical Interface

• Bipolar



• Unipolar



Special requirements upon customer specifications. Right to change reserved.

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